
石头 - 剪刀 - 布的统计物理学

STAT-PHYS OF ROCK-PAPER-SCISSORS

周海军

中国科学院理论物理研究所

合作者:

王志坚（浙江大学实验社会学实验室）、许彬（浙江工商大学公共管理学院）

Zhijian Wang, Bin Xu, Hai-Jun Zhou*,

Social cycling and conditional responses in the Rock-Paper-Scissors game,

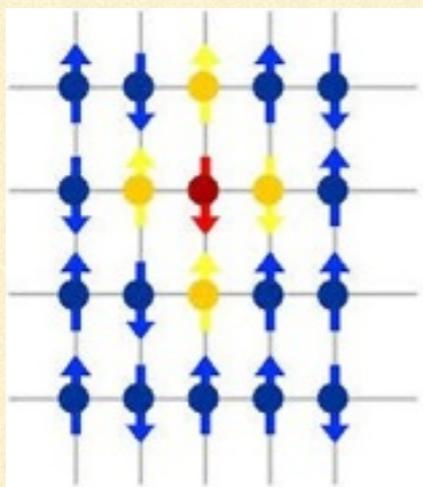
arXiv:1404.5199 (April 21, 2014)

STAT-PHYSICS AS A BRIDGE



macroscopic phenomena

* infer micro-interactions from macro-properties
(the **inverse** problem)

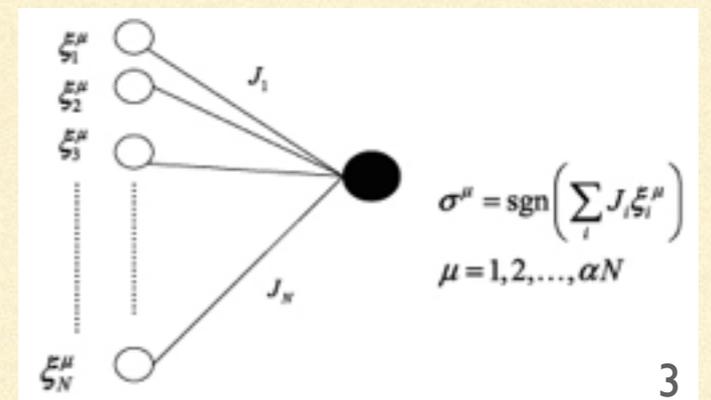
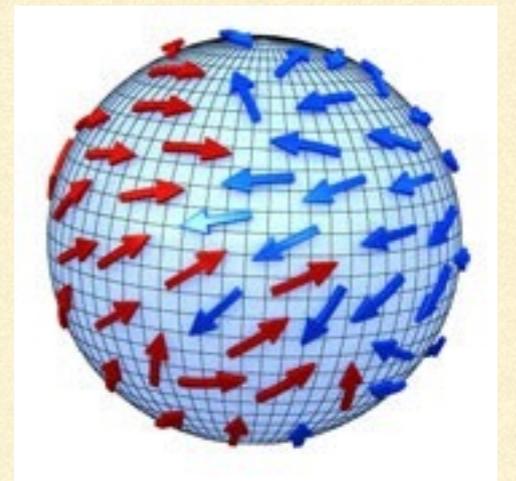


* predict macro-properties from micro-interactions
(the **direct** problem)

microscopic interactions

我们研究小组

- **自旋玻璃**：平均场理论、消息传播算法、组合优化、约束满足、复杂网络 (小册子即将出版)
- **博弈动力学**：决策、非平衡演化、优化
- **学习动力学**：神经网络、学习微观机制



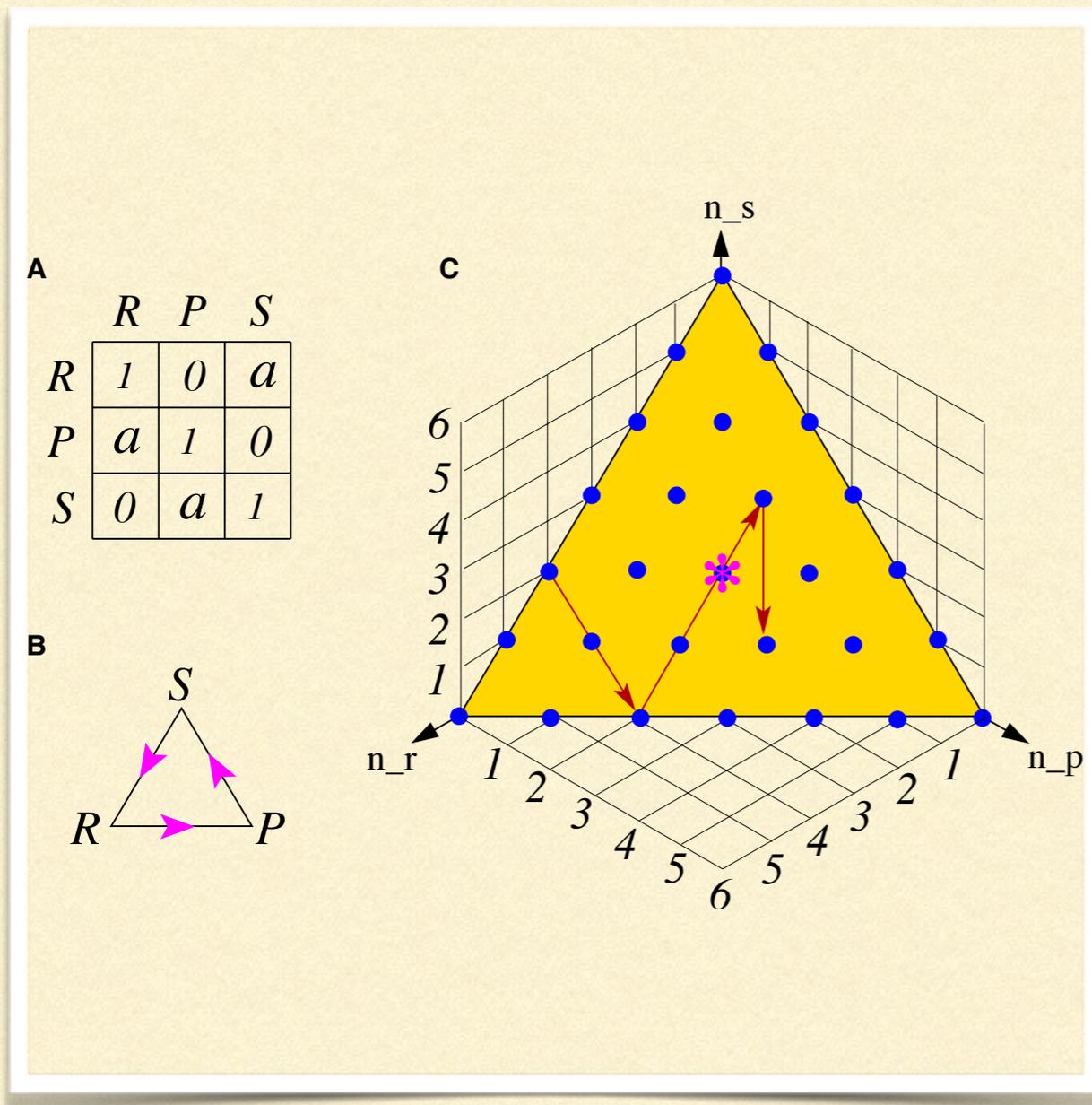
面向交叉学科，面向复杂系统



OUTLINE

- background
- experimental setup
- experimental observations
- theoretical modeling
- discussions

ROCK-PAPER-SCISSORS GAME



- Basic model of non-cooperative strategic interactions
- Only single parameter: payoff a of winning action
- For a population of N players, social state denoted as (n_r, n_p, n_s)
- social state evolution

EXPERIMENTAL SET-UP



- Finite population, $N=6$
- **Random pairwise-matching**: at each game round, a player competes with a random opponent
- win: a points;
tie: 1 point
lose: 0 point
- Game repeats 300 rounds
- **Feedback information**: own payoff;
own action; opponent's action;
own accumulate payoff

payoff parameter a :

$a = 1.1$ (11 populations, NE non-stable)

$a = 2$ (12 populations, NE neutral)

$a = 4$ (12 populations, NE stable)

$a = 9$ (12 populations, NE stable)

$a = 100$ (12 populations, NE stable)

CLASSICAL GAME THEORY VS EVOLUTIONARY GAME THEORY

CGT: Nash (1950)

- complete rationality.
- mixed-strategy Nash equilibrium.

$\begin{matrix} 1 \\ 2 \\ 3 \end{matrix}$ – R
– P for each player
– S at each game round

- social dynamics trivial (detailed balance).

EGT: Maynard Smith (1973)

- bounded rationality
- microscopic evolutionary mechanisms or learning mechanisms
- breaking of detailed balance.
- individual- and/or social-level **cycling**.

OUR QUESTION

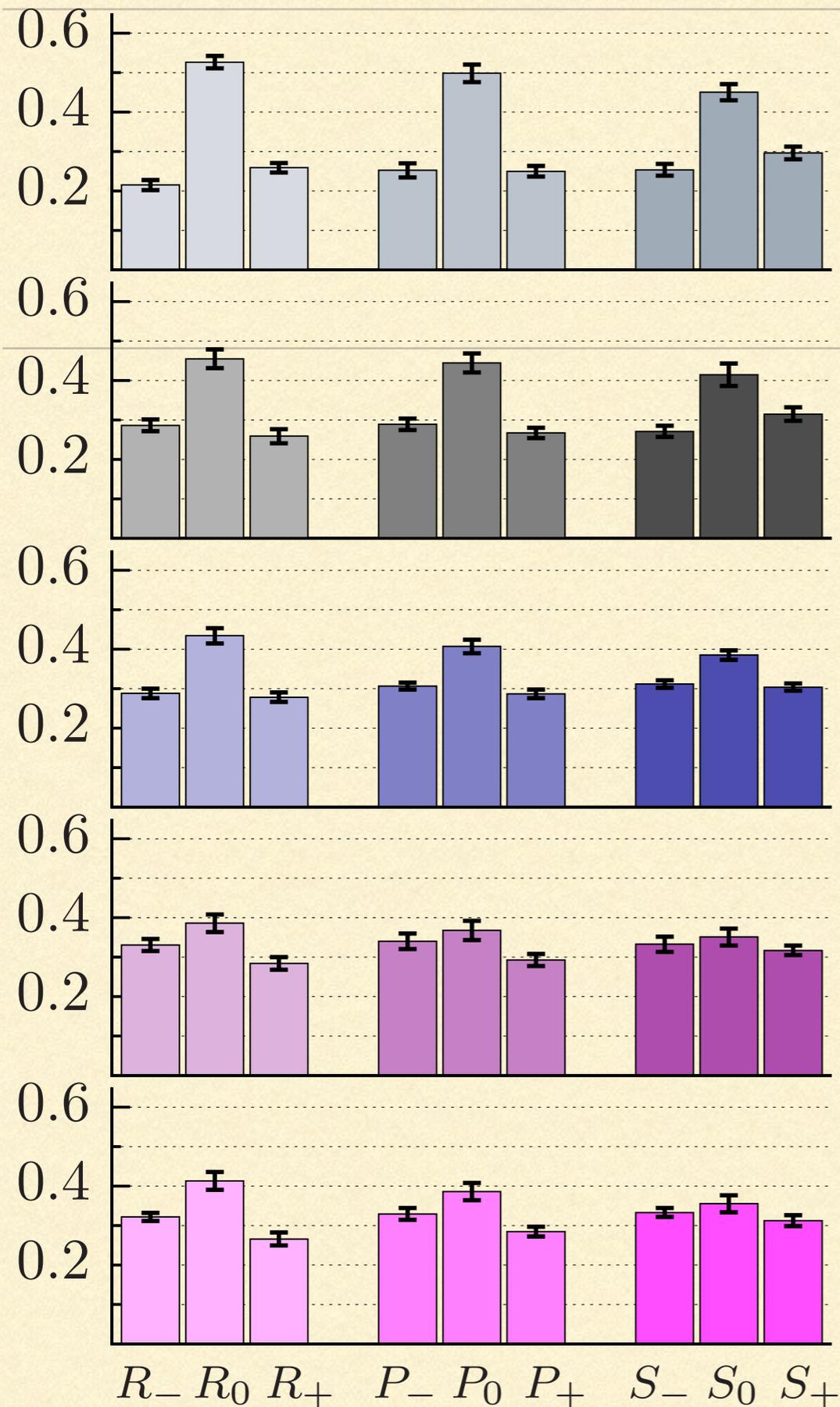
Resolution of CGT—EGT debate in human subjects systems rather challenging:

- 1) Experimental data very noisy;
- 2) Experiments can't take sufficiently long;
- 3) Game theorists are mainly mathematicians (they love paper work) ...

How humans make decisions in non-cooperative situations **under only partial information?**

The finite-population RPS game.

BEHAVIOR OF INDIVIDUAL PLAYER



- Individual players change actions frequently:

R: 0.36 ± 0.08 (mean \pm s.d.)

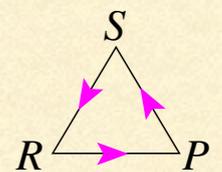
P: 0.33 ± 0.07

S: 0.32 ± 0.06

consistent with Nash equilibrium

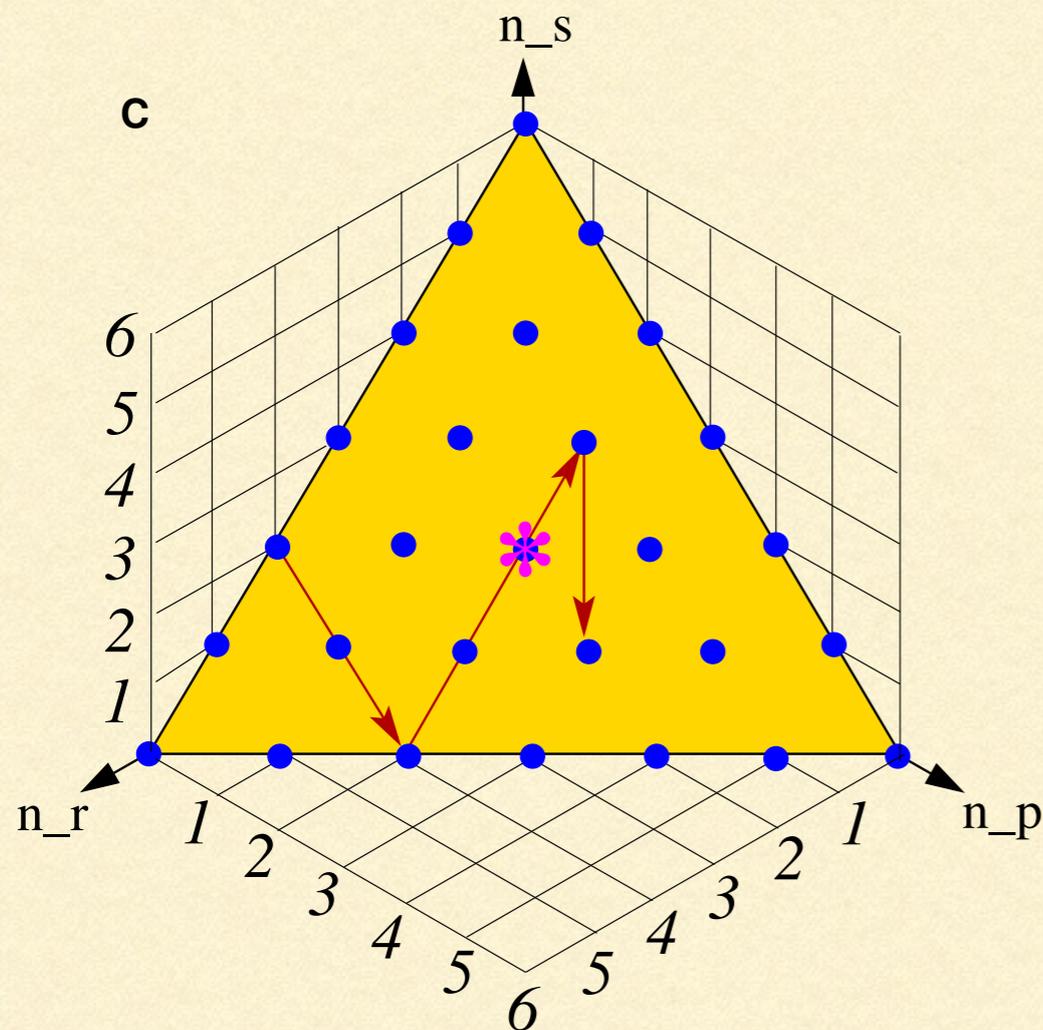
- Inertial effect: more likely to choose same action than to shift action either clockwise (-) or counter-clockwise (+)

different with Nash equilibrium



- No individual-level cycling.

COLLECTIVE BEHAVIOR: ROTATION AROUND CENTROID

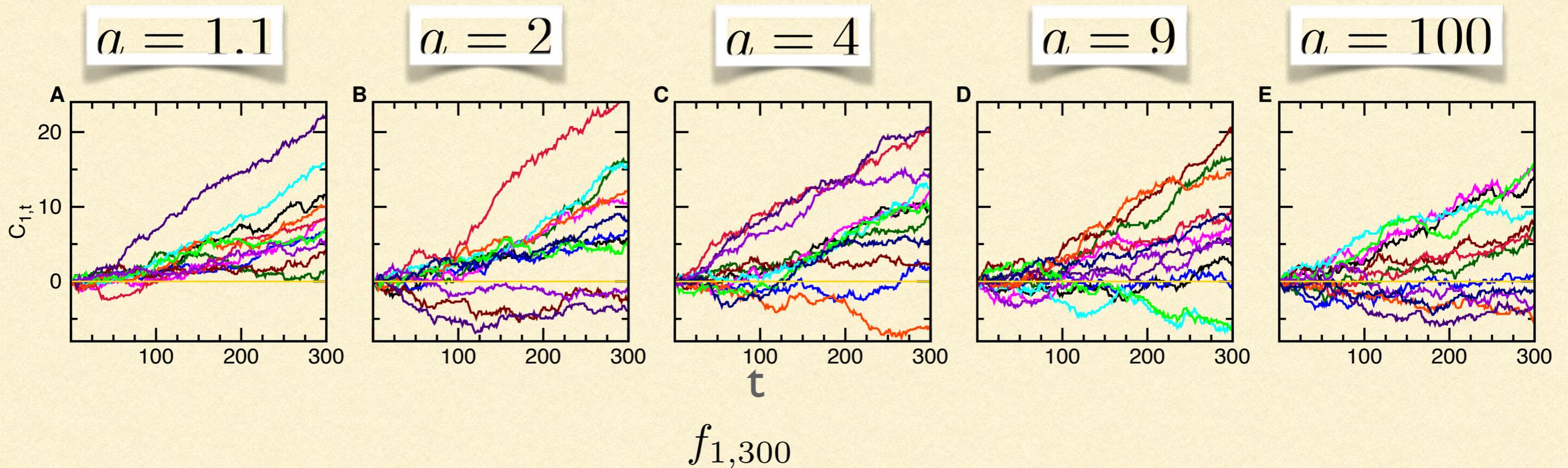


- rotation number:

$$C_{t_0, t_1} \equiv \sum_{t=t_0}^{t_1-1} \frac{\theta(t)}{2\pi}$$

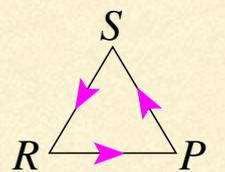
- rotation frequency:

$$f_{t_0, t_1} \equiv \frac{C_{t_0, t_1}}{t_1 - t_0}$$



mean	0.031	0.027	0.031	0.022	0.018
s.d.	0.019	0.029	0.026	0.027	0.025
s.e.m.	0.006	0.008	0.008	0.008	0.007

Population-level cyclic motions exist and persist
 (about 1 turn in 35 game rounds).
 Cycling direction is counter-clockwise.

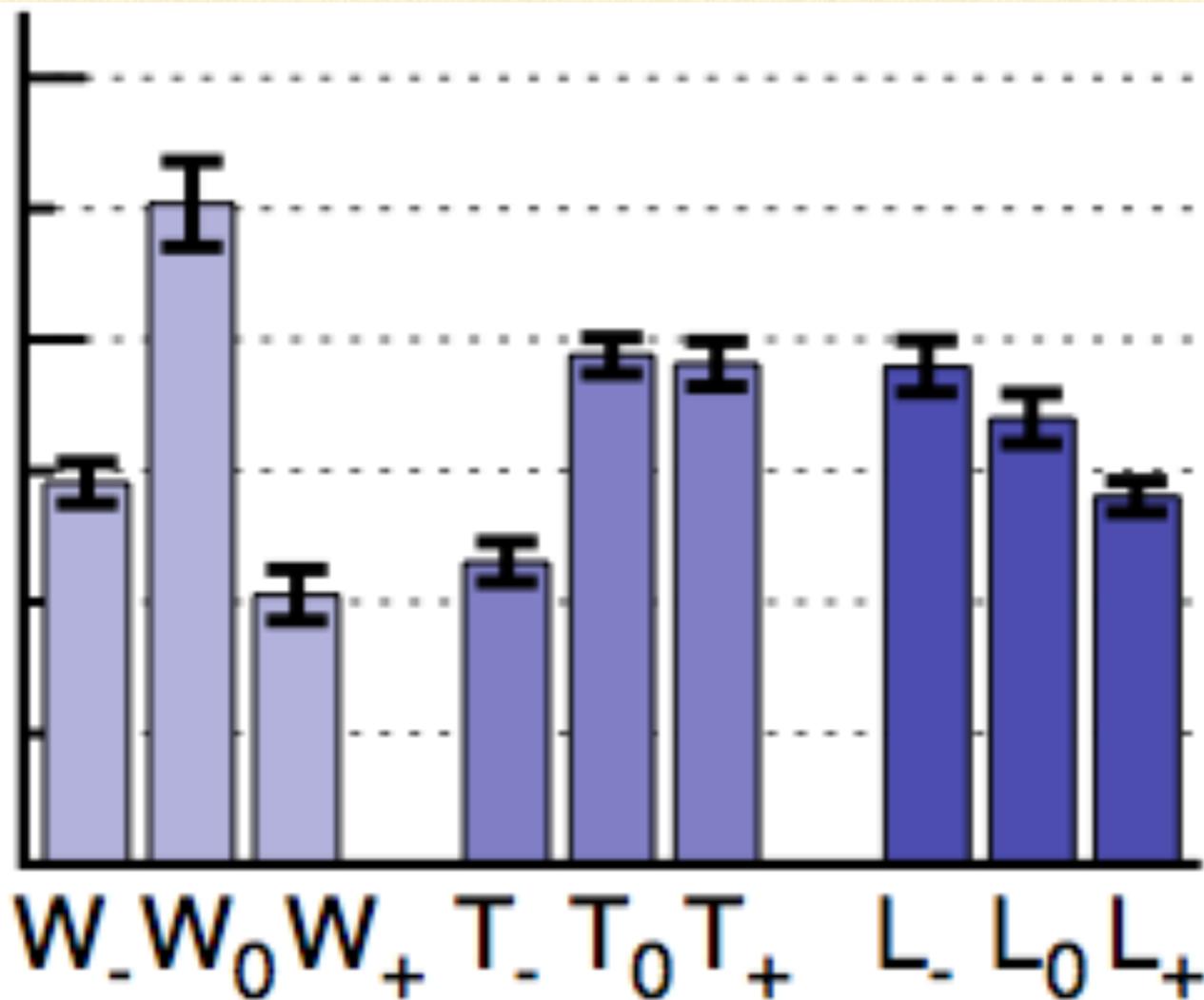


WHY SOCIAL-LEVEL CYCLING?

- Cannot be explained by Nash equilibrium theory (infinite rationality).
- Cannot be explained by assuming players make decisions independently of each other.
- Let's get inspirations from empirical data!!!

$$a = 4$$

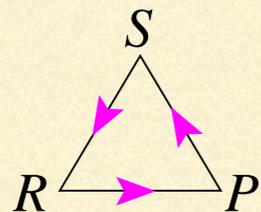
CONDITIONAL RESPONSES



- play outcome:

W (win), T (tie), L (lose)

- e.g., if W (win) , next step:



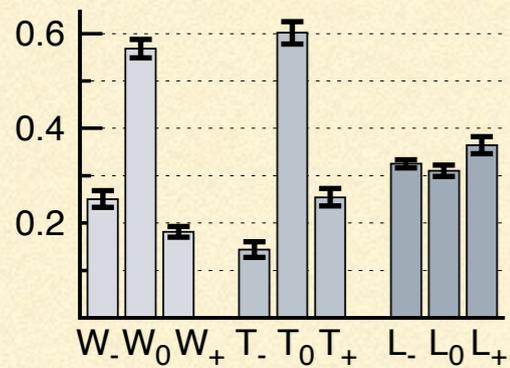
keep old action (prob W_0)

shift action clockwise (prob W_-)

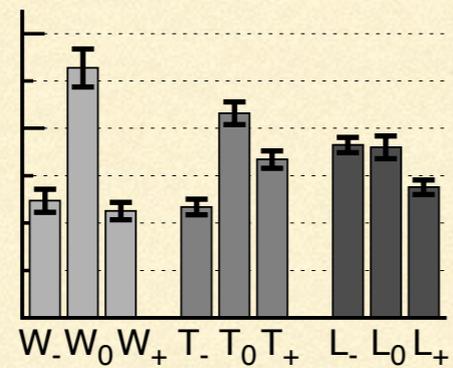
shift action counter-clockwise (prob W_+)

CONDITIONAL RESPONSES

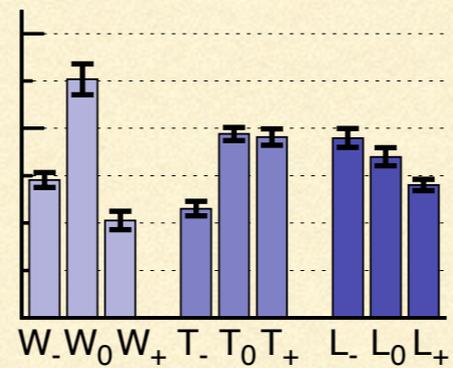
$a = 1.1$



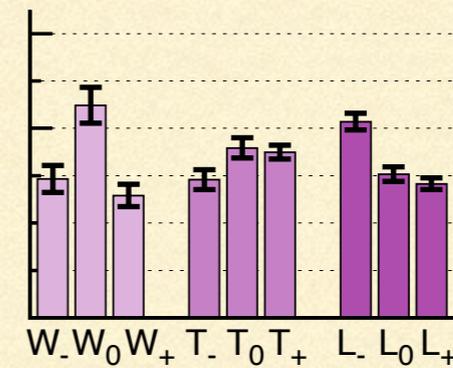
$a = 2$



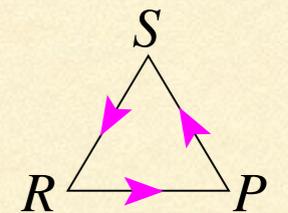
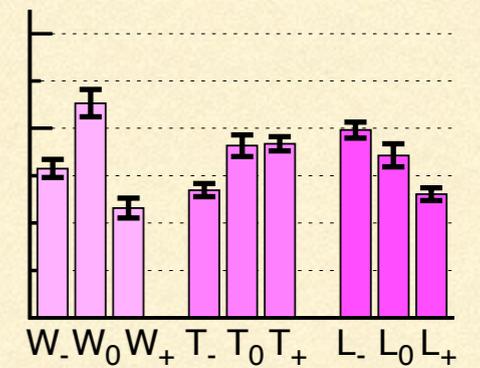
$a = 4$



$a = 9$



$a = 100$



MODEL BASED ON CR-STRATEGY

At each step, every player of the population chooses an action in a probabilistic way of conditional response:

Given the outcome of the **current** play being

$$O \in \{W, T, L\}$$

In the **next** play, the player will choose to

—keep the same action with probability O_0

—shift action clock wisely (R->S, S->R, P->R) with probability O_-

—shift action counter clock wisely (R->P, P->S, S->R) with probability O_+

$$\begin{aligned}
M_{Cr}[\mathbf{s}'|\mathbf{s}] &= \sum_{n_{rr}, n_{pp}, \dots, n_{sr}} \frac{n_R! n_P! n_S! \delta_{2n_{rr}+n_{sr}+n_{rp}}^{n_R} \delta_{2n_{pp}+n_{rp}+n_{ps}}^{n_P} \delta_{2n_{ss}+n_{ps}+n_{sr}}^{n_S}}{(N-1)!! 2^{n_{rr}} n_{rr}! 2^{n_{pp}} n_{pp}! 2^{n_{ss}} n_{ss}! n_{rp}! n_{ps}! n_{sr}!} \\
&\times \sum_{n_{rr}^{rr}, \dots, n_{rr}^{sr}} \frac{n_{rr}! T_0^{2n_{rr}^{rr}} T_+^{2n_{rr}^{pp}} T_-^{2n_{rr}^{ss}} (2T_+T_0)^{n_{rr}^{rp}} (2T_+T_-)^{n_{rr}^{ps}} (2T_0T_-)^{n_{rr}^{sr}}}{n_{rr}^{rr}! n_{rr}^{pp}! n_{rr}^{ss}! n_{rr}^{rp}! n_{rr}^{ps}! n_{rr}^{sr}!} \delta_{n_{rr}^{rr} + \dots + n_{rr}^{sr}} \\
&\times \sum_{n_{pp}^{rr}, \dots, n_{pp}^{sr}} \frac{n_{pp}! T_-^{2n_{pp}^{rr}} T_0^{2n_{pp}^{pp}} T_+^{2n_{pp}^{ss}} (2T_0T_-)^{n_{pp}^{rp}} (2T_+T_0)^{n_{pp}^{ps}} (2T_+T_-)^{n_{pp}^{sr}}}{n_{pp}^{rr}! n_{pp}^{pp}! n_{pp}^{ss}! n_{pp}^{rp}! n_{pp}^{ps}! n_{pp}^{sr}!} \delta_{n_{pp}^{rr} + \dots + n_{pp}^{sr}} \\
&\times \sum_{n_{ss}^{rr}, \dots, n_{ss}^{sr}} \frac{n_{ss}! T_+^{2n_{ss}^{rr}} T_-^{2n_{ss}^{pp}} T_0^{2n_{ss}^{ss}} (2T_+T_-)^{n_{ss}^{rp}} (2T_0T_-)^{n_{ss}^{ps}} (2T_+T_0)^{n_{ss}^{sr}}}{n_{ss}^{rr}! n_{ss}^{pp}! n_{ss}^{ss}! n_{ss}^{rp}! n_{ss}^{ps}! n_{ss}^{sr}!} \delta_{n_{ss}^{rr} + \dots + n_{ss}^{sr}} \\
&\times \sum_{n_{rp}^{rr}, \dots, n_{rp}^{sr}} \frac{n_{rp}! \delta_{n_{rp}^{rr} + \dots + n_{rp}^{sr}}}{n_{rp}^{rr}! n_{rp}^{pp}! n_{rp}^{ss}! n_{rp}^{rp}! n_{rp}^{ps}! n_{rp}^{sr}!} (W_-L_0)^{n_{rp}^{rr}} (W_0L_+)^{n_{rp}^{pp}} (W_+L_-)^{n_{rp}^{ss}} \\
&\quad \times (W_0L_0 + W_-L_+)^{n_{rp}^{rp}} (W_+L_+ + W_0L_-)^{n_{rp}^{ps}} (W_+L_0 + W_-L_-)^{n_{rp}^{sr}} \\
&\times \sum_{n_{ps}^{rr}, \dots, n_{ps}^{sr}} \frac{n_{ps}! \delta_{n_{ps}^{rr} + \dots + n_{ps}^{sr}}}{n_{ps}^{rr}! n_{ps}^{pp}! n_{ps}^{ss}! n_{ps}^{rp}! n_{ps}^{ps}! n_{ps}^{sr}!} (W_+L_-)^{n_{ps}^{rr}} (W_-L_0)^{n_{ps}^{pp}} (W_0L_+)^{n_{ps}^{ss}} \\
&\quad \times (W_+L_0 + W_-L_-)^{n_{ps}^{rp}} (W_0L_0 + W_-L_+)^{n_{ps}^{ps}} (W_+L_+ + W_0L_-)^{n_{ps}^{sr}} \\
&\times \sum_{n_{sr}^{rr}, \dots, n_{sr}^{sr}} \frac{n_{sr}! \delta_{n_{sr}^{rr} + \dots + n_{sr}^{sr}}}{n_{sr}^{rr}! n_{sr}^{pp}! n_{sr}^{ss}! n_{sr}^{rp}! n_{sr}^{ps}! n_{sr}^{sr}!} (W_0L_+)^{n_{sr}^{rr}} (W_+L_-)^{n_{sr}^{pp}} (W_-L_0)^{n_{sr}^{ss}} \\
&\quad \times (W_+L_+ + W_0L_-)^{n_{sr}^{rp}} (W_+L_0 + W_-L_-)^{n_{sr}^{ps}} (W_0L_0 + W_-L_+)^{n_{sr}^{sr}} \\
&\times \delta_{2(n_{rr}^{rr}+n_{rr}^{pp}+n_{rr}^{ss}+n_{rr}^{rp}+n_{rr}^{ps}+n_{rr}^{sr})+(n_{sr}^{rr}+n_{sr}^{pp}+n_{sr}^{ss}+n_{sr}^{rp}+n_{sr}^{ps}+n_{sr}^{sr})+(n_{rp}^{rr}+n_{rp}^{pp}+n_{rp}^{ss}+n_{rp}^{rp}+n_{rp}^{ps}+n_{rp}^{sr})} \\
&\times \delta_{2(n_{pp}^{rr}+n_{pp}^{pp}+n_{pp}^{ss}+n_{pp}^{rp}+n_{pp}^{ps}+n_{pp}^{sr})+(n_{rr}^{rp}+n_{rr}^{pp}+n_{rr}^{ss}+n_{rr}^{rp}+n_{rr}^{ps}+n_{rr}^{sr})+(n_{ps}^{rr}+n_{ps}^{pp}+n_{ps}^{ss}+n_{ps}^{rp}+n_{ps}^{ps}+n_{ps}^{sr})} \\
&\times \delta_{2(n_{ss}^{rr}+n_{ss}^{pp}+n_{ss}^{ss}+n_{ss}^{rp}+n_{ss}^{ps}+n_{ss}^{sr})+(n_{rr}^{ps}+n_{rr}^{ps}+n_{rr}^{ps}+n_{rr}^{ps}+n_{rr}^{ps}+n_{rr}^{ps})+(n_{sr}^{sr}+n_{sr}^{pp}+n_{sr}^{ss}+n_{sr}^{rp}+n_{sr}^{ps}+n_{sr}^{sr})}
\end{aligned}$$

$a = 1.1$

$a = 2$

$a = 4$

$a = 9$

$a = 100$

$f_{1,300}$

mean	0.031	0.027	0.031	0.022	0.018
s.d.	0.019	0.029	0.026	0.027	0.025
s.e.m.	0.006	0.008	0.008	0.008	0.007

$a = 1.1$

$a = 2$

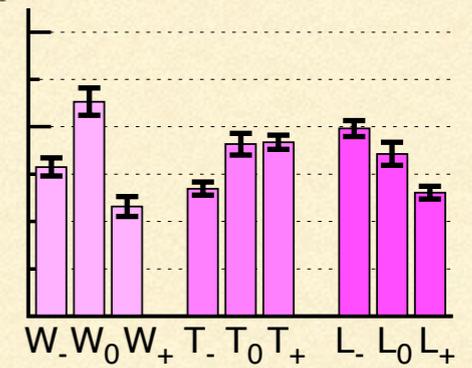
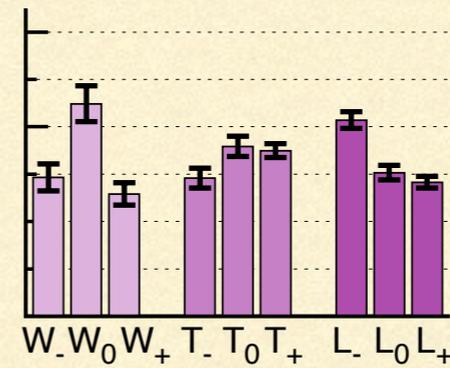
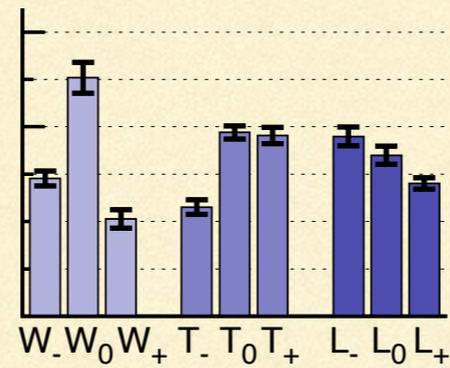
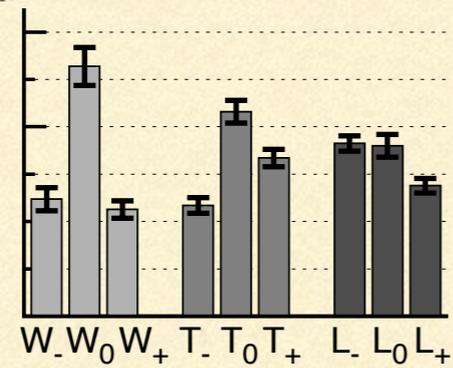
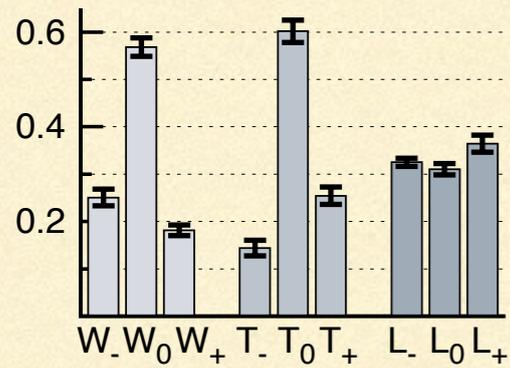
$a = 4$

$a = 9$

$a = 100$

$f_{1,300}$

mean	0.031	0.027	0.031	0.022	0.018
s.d.	0.019	0.029	0.026	0.027	0.025
s.e.m.	0.006	0.008	0.008	0.008	0.007



model: 0.035

0.026

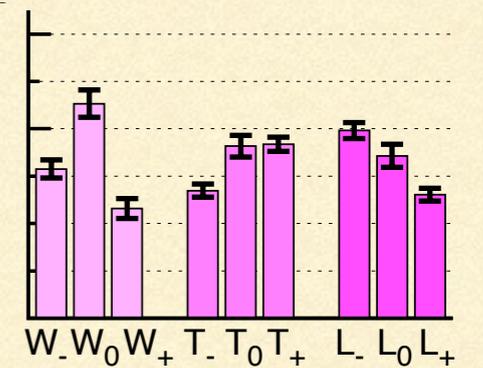
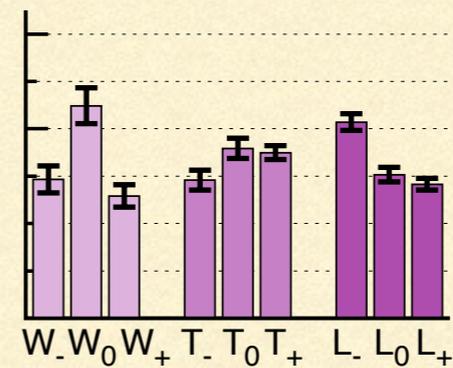
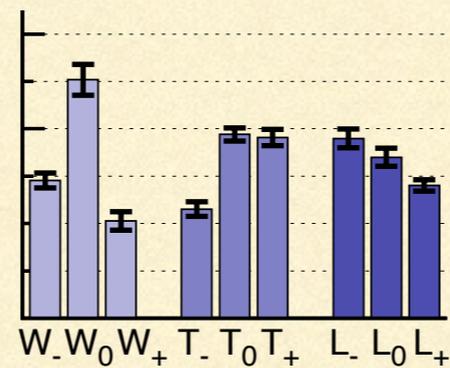
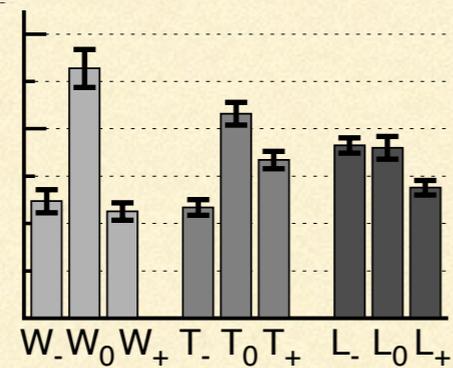
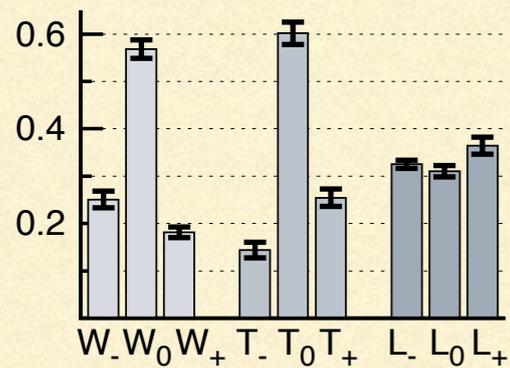
0.030

0.018

0.017

$a = 1.1$ $a = 2$ $a = 4$ $a = 9$ $a = 100$ $f_{1,300}$

mean	0.031	0.027	0.031	0.022	0.018
s.d.	0.019	0.029	0.026	0.027	0.025
s.e.m.	0.006	0.008	0.008	0.008	0.007



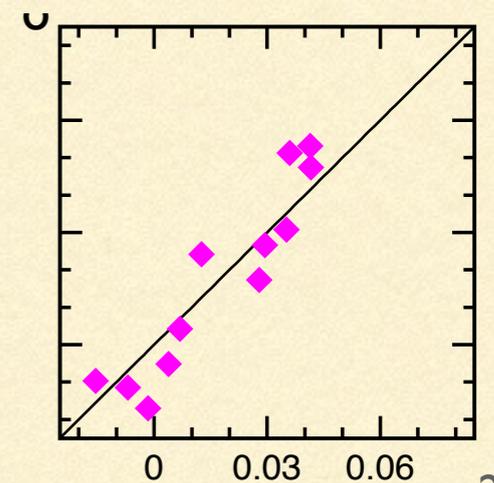
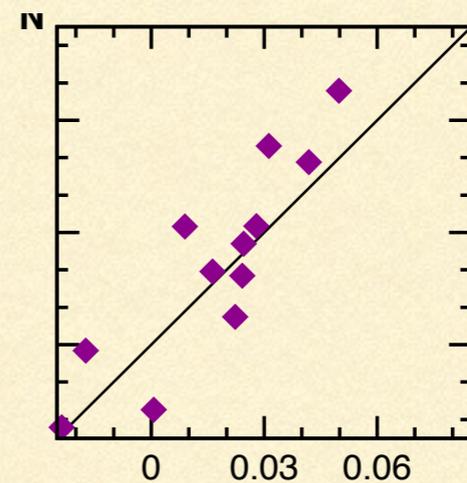
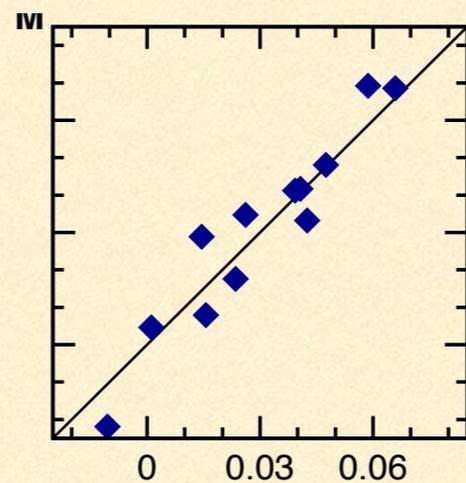
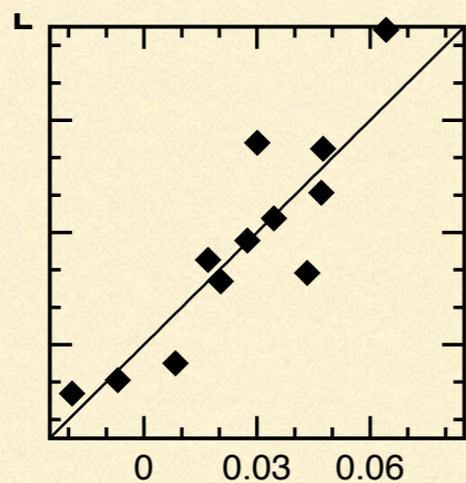
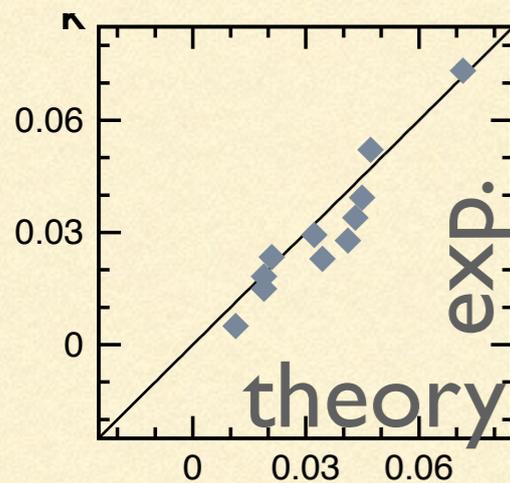
model: 0.035

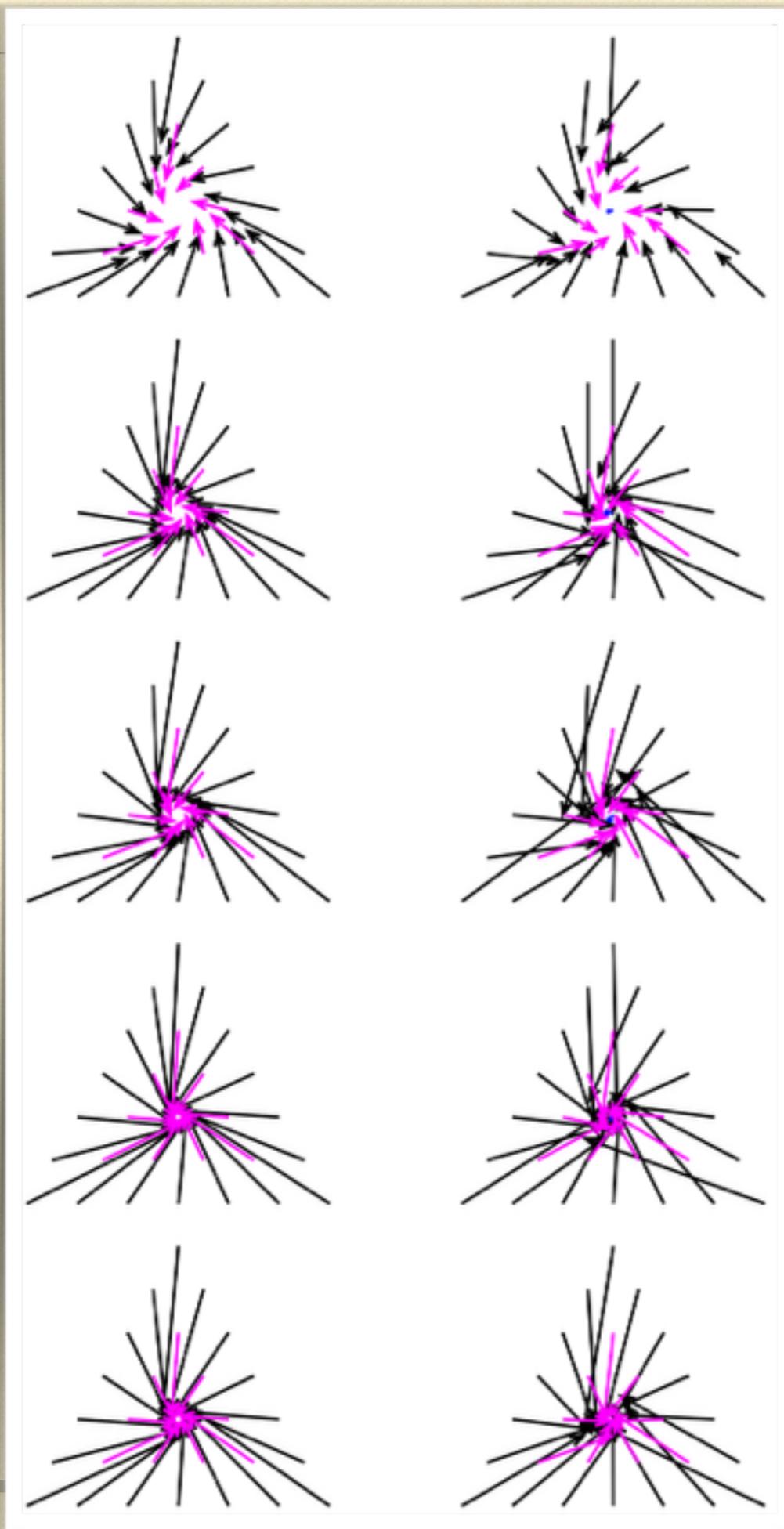
0.026

0.030

0.018

0.017

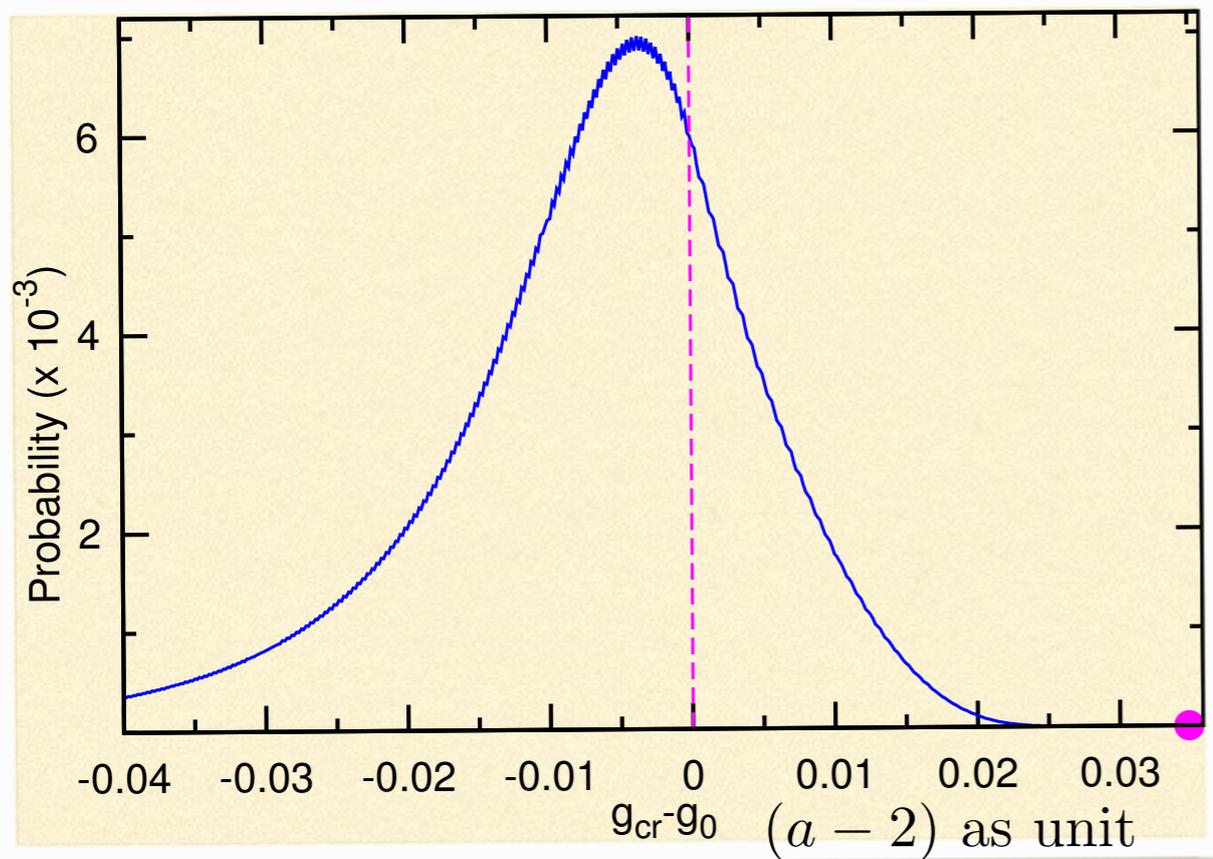




CR-MODEL EXPLAINS CYCLING

- social cycling can be quantitatively explained by the model of conditional response.
- If a player wins over her opponent her opponent in one play, her probability of repeating the same action is considerably higher than her probabilities of shifting actions.
- If a player loses to her opponent in one play, she is more likely to shift action clockwise (R->S, P->R, S->P) than either to keep the old action or to shift action counter-clockwise.

BENEFIT OF CR-STRATEGY?



$$g_0 = \frac{1+a}{3} \quad \text{NE mixed-strategy}$$

$$g_{cr} \quad \text{CR-strategy}$$

- 2,400,000,000 CR-strategies sampled uniformly at random to obtain the mean payoff distribution.
- CR-strategy has high probability of being inferior to NE mixed-strategy.
- Yet, optimized CR-strategies can outperform NE mixed-strategy by 10% (for population size $N=6$).
- Empirical mean payoff slightly outperforms NE mixed-strategy.

SOME GOOD CR-STRATEGIES (I)

$$W_- = 0.002 \quad T_- = 0.067 \quad L_- = 0.003$$

$$W_0 = 0.998 \quad T_0 = 0.823 \quad L_0 = 0.994$$

$$W_+ = 0.000 \quad T_+ = 0.110 \quad L_+ = 0.003$$

lazy, but not too lazy

$$f_{cr} = 0.003 \quad g_{cr} = g_0 + 0.035(a - 2)$$

SOME GOOD CR-STRATEGIES (2)

$$W_- = 0.995 \quad T_- = 0.800 \quad L_- = 0.988$$

$$W_0 = 0.004 \quad T_0 = 0.142 \quad L_0 = 0.000$$

$$W_+ = 0.001 \quad T_+ = 0.058 \quad L_+ = 0.012$$

coordinated

$$f_{cr} = -0.190 \quad g_{cr} = g_0 + 0.034(a - 2)$$

SOME GOOD CR-STRATEGIES (3)

$$W_- = 0.001 \quad T_- = 0.063 \quad L_- = 0.989$$

$$W_0 = 0.994 \quad T_0 = 0.146 \quad L_0 = 0.010$$

$$W_+ = 0.005 \quad T_+ = 0.791 \quad L_+ = 0.001$$

win-stay, lose-shift

$$f_{cr} = 0.189 \quad g_{cr} = g_0 + 0.033(a - 2)$$

OUTLOOK

- CR-strategy leads to social cycling, and may even lead to social efficiency. Yet how to **optimize** its parameters **by learning**?
- **Whether Conditional response is a basic decision-making mechanism of the human brain or just a consequence of more fundamental neural mechanisms is a challenging issue for future studies.**
- Let data speak.

ACKNOWLEDGEMENTS

- 王志坚、许彬，参与实验的360名浙江大学同学，和实验员
- 欧阳钟灿老师
- 理论物理国家重点实验室，国家自然科学基金委，中科院交叉基金
- 理论物理研究所hpc计算机集群，及金洪波博士

数据
懂数据
超越数据
(但别超太多)